

EXACT SOLUTIONS OF THE STOCHASTIC NAVIER-STOKES EQUATIONS

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Abstract. This report develops a class of exact solutions based on Green-Taylor's vortex [5], [6] to stochastic Navier-Stokes equations to test the accuracy of the various models and methods.

Key Words: Stochastic Navier-Stokes, Green-Taylor vortex.

Mathematics Subject Classification:

1. Introduction. In Computational Fluid Dynamics (CFD), all the approaches to Uncertainty Quantification (UQ) seek to quantify the uncertainty in approximations to the expectation, moments and other statistical quantities of interest in a flow. Validation of various approaches (e.g., polynomial chaos [7], stochastic collocation [8]) to UQ in CFD requires as a first step exact solutions of the stochastic NSE with with stochasticity introduced in various places. In this report, we present exact solutions of the stochastic Navier-Stokes equations extending the Green-Taylor vortex solutions [1] to include stochastic forcing, initial conditions and viscosity. Green-Taylor vortex solutions have been extensively used in CFD, see e.g. [4], [3].

For a random variable ξ , we therefore consider the stochastic Navier-Stokes equations with stochasticity introduced in

- (i) the body force by a Brownian motion $\mathbf{f} = \sigma \dot{W}(t)$ with $\sigma = \text{const}$, or
- (ii) the initial condition $\mathbf{u}(x, 0; \xi) = \mathbf{a}(x)g(\xi)$, or
- (iii) the viscosity $\nu(\xi)$.

Let $\mathbf{a}(x)$ be a Stokes eigenfunction

$$\Delta \mathbf{a} = \lambda \mathbf{a}, \quad \nabla \cdot \mathbf{a} = 0 \text{ in } \Omega \text{ and } \mathbf{a}(x) = \mathbf{0} \text{ on } \partial\Omega. \quad (1.1)$$

Let $\mathbf{u}(x, t; \xi)$, $x \in \Omega \subset \mathbb{R}^2$ satisfy

$$\begin{cases} \mathbf{u}_t + \mathbf{u} \cdot \nabla \mathbf{u} - \nu \Delta \mathbf{u} + \nabla p = \mathbf{f}, \\ \nabla \cdot \mathbf{u} = 0, \\ \mathbf{u} = \mathbf{0} \text{ on } \partial\Omega, \\ \mathbf{u}(x, 0; \xi) = \mathbf{a}(x)g(\xi). \end{cases} \quad (1.2)$$

We prove the following:

THEOREM 1.1.

- (i) If $\mathbf{f} = \sigma \dot{W}(t)$ with $\sigma = \text{const}$, $\nu = \text{const}$ and $g \equiv 1$, then the exact solution of (1.2) is

$$\mathbf{u}(x, t) = \mathbf{a} \left(x - \int_0^t \sigma W(s) ds \right) e^{\lambda \nu t} + \sigma W(t), \quad (1.3)$$

$$\nabla p(x, t) = -(\mathbf{u} - \sigma W(t)) \cdot \nabla \mathbf{u}. \quad (1.4)$$

- (ii) If $\mathbf{f} = \mathbf{0}$, $\nu = \text{const}$ and $g = g(\xi)$, then the exact solution of (1.2) is

$$\mathbf{u}(x, t; \xi) = e^{\lambda \nu t} \mathbf{a}(x)g(\xi), \quad (1.5)$$

$$\nabla p(x, t; \xi) = -\mathbf{u}(x, t; \xi) \cdot \nabla \mathbf{u}(x, t; \xi). \quad (1.6)$$

- (iii) If $\mathbf{f} = \mathbf{0}$, $\nu = \nu(\xi)$ and $g \equiv 1$, then the exact solution of (1.2) is

$$\mathbf{u}(x, t; \xi) = e^{\lambda \nu(\xi) t} \mathbf{a}(x), \quad (1.7)$$

$$\nabla p(x, t; \xi) = -\mathbf{u}(x, t; \xi) \cdot \nabla \mathbf{u}(x, t; \xi). \quad (1.8)$$

These are the stochastic extensions of the famous Green-Taylor vortices.

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2. The proof. First, we will briefly recall the construction of the Green-Taylor solution to deterministic Navier-Stokes equations

$$\mathbf{v}_t + \mathbf{v} \cdot \nabla \mathbf{v} = \nu \Delta \mathbf{v} - \nabla q, \quad \nabla \cdot \mathbf{v} = 0 \quad \text{and} \quad \mathbf{v}(x, 0) = \mathbf{a}(x). \quad (2.1)$$

LEMMA 2.1. (from [1]). Suppose $\mathbf{a}(x)$ satisfies (1.1). Then $\mathbf{v} = e^{\nu \lambda t} \mathbf{a}$ satisfies $\nabla \times (\mathbf{v} \cdot \nabla \mathbf{v}) = \mathbf{0}$ and (2.1) with pressure q such that $\nabla q = -\mathbf{v} \cdot \nabla \mathbf{v}$.

Proof. Since $\nabla \cdot \mathbf{a} = 0$, then $\nabla \cdot \mathbf{u} = 0$. Further, $\mathbf{u}_t = \nu \lambda \mathbf{u} = \nu \Delta \mathbf{u}$ and hence it only remains to prove that nonlinear term is a gradient. This is equivalent to showing

$$\frac{\partial}{\partial y} \left(u_1 \frac{\partial u_1}{\partial x} + u_2 \frac{\partial u_1}{\partial y} \right) = \frac{\partial}{\partial x} \left(u_1 \frac{\partial u_2}{\partial x} + u_2 \frac{\partial u_2}{\partial y} \right), \quad (2.2)$$

which directly follows from (1.1). \square

$$\begin{aligned} u_1(x, t) &= -\cos(n\pi x) \sin(n\pi y) e^{-2\pi^2 n^2 \nu t}, \\ u_2(x, t) &= \sin(n\pi x) \cos(n\pi y) e^{-2\pi^2 n^2 \nu t}, \\ p(x, t) &= -\frac{1}{4} (\cos(2n\pi x) + \cos(2n\pi y)) e^{-4\pi^2 n^2 \nu t}, \end{aligned}$$

which corresponds to $\lambda = -2\pi^2 n^2$, where n is any positive integer. Different linear combinations of eigenfunctions corresponding to λ gives rise to complex flow patterns [1].

Proof of the Theorem 1.1. From [1], it follows that if $\mathbf{a}(x)$ is a Stokes eigenfunction and since, for the last two cases in Theorem 1.1, $\mathbf{u}(x, t; \xi)$ takes the form $\mathbf{u} = \mathbf{a}(x)G(t, \xi)$, we have that $\nabla \times (\mathbf{u} \cdot \nabla \mathbf{u}) \equiv \mathbf{0}$. Then, as in [1], nonlinearity is balanced by the pressure $\nabla p = -\mathbf{u} \cdot \nabla \mathbf{u}$.

- (i) Note that by using Ito's formula [2], the solution of (2.1), (\mathbf{v}, q) is related to that of (1.2) by

$$\begin{cases} \mathbf{u}(x, t) = \mathbf{v} \left(x - \int_0^t \sigma W(s) ds, t \right) + \sigma W(t), \\ p(x, t) = q \left(x - \int_0^t \sigma W(s) ds, t \right). \end{cases} \quad (2.3)$$

Thus, by Lemma 2.1 we have that

$$\mathbf{u}(x, t) = \mathbf{a} \left(x - \int_0^t \sigma W(s) ds \right) e^{\lambda \nu t} + \sigma W(t), \quad (2.4)$$

along with $\mathbf{u}(x, 0) = \mathbf{a}(x)$. Since $\nabla q = -\mathbf{v} \cdot \nabla \mathbf{v} = (\sigma W(t) - \mathbf{u}) \cdot \nabla \mathbf{u}$, we obtain that

$$\nabla \times (\sigma W(t) - \mathbf{u}) \cdot \nabla \mathbf{u} = \mathbf{0}.$$

Therefore,

$$\nabla p(x, t) = (\sigma W(t) - \mathbf{u}) \cdot \nabla \mathbf{u}. \quad (2.5)$$

- (ii) Obviously, $\mathbf{u} = e^{\lambda \nu t} g(\xi) \mathbf{a}(x)$ satisfies the initial and boundary conditions. The rest of the proof follows from Lemma 2.1.
(iii) By Lemma 2.1, $\mathbf{u}(x, t; \xi) = e^{\lambda \nu(\xi)t} \mathbf{a}(x)$ satisfies

$$\mathbf{u}_t(x, t; \xi) = \lambda \nu(\xi) \mathbf{u}(x, t; \xi) = \nu(\xi) \Delta \mathbf{u}(x, t; \xi).$$

Further, as mentioned in the beginning of the proof, $\mathbf{u}(x, t; \xi) \cdot \nabla \mathbf{u}(x, t; \xi)$ is gradient.

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